

Calculus summary handout 1

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1 Logarithm and exponential function

Two important functions in statistical pattern recognition are the exponential function and the logarithm (they are actually each others inverses).

1.1 Exponential function

Some properties:

$$\begin{aligned}\exp(x) \exp(y) &= \exp(x + y) \\ (\exp(x))^a &= \exp(ax) \\ 1/\exp(x) &= \exp(-x) \\ \exp(0) &= 1 \\ \frac{d}{dx} \exp(x) &= \exp(x)\end{aligned}$$

In addition, it has the following limits,

$$\lim_{x \rightarrow -\infty} \exp(x) = 0 \quad (1)$$

$$\lim_{x \rightarrow \infty} \exp(x) = \infty \quad (2)$$

where it should be noted that the exponential function is a very rapidly increasing function: for any power n (no matter how large) $x^n/\exp(x) \rightarrow 0$ if $x \rightarrow \infty$. In words: 'the exponential function wins from any power'.

1.2 Logarithm

The logarithm is written as $\log(x)$ or $\ln(x)$. Unless stated otherwise, the logarithm is to the base of e (or: natural logarithm), even if it is written as $\log(x)$. The logarithm is only defined for positive x (we will not deal with complex numbers).

Properties:

$$\log(xy) = \log(x) + \log(y) \quad (3)$$

$$\log(x/y) = \log(x) - \log(y) \quad (4)$$

$$\log(x^a) = a \log(x) \quad (5)$$

$$\log(1/x) = -\log(x) \quad (6)$$

$$\log(1) = 0 \quad (7)$$

$$\frac{d}{dx} \log(x) = \frac{1}{x} \quad (8)$$

In addition, it has the following limits,

$$\lim_{x \downarrow 0} \log(x) = -\infty \quad (9)$$

$$\lim_{x \rightarrow \infty} \log(x) = \infty \quad (10)$$

where it should be noted that the logarithmic function is a very slowly increasing function: for any power $\alpha > 0$ (no matter how small), $\log(x)/x^\alpha \rightarrow 0$ if $x \rightarrow \infty$. In words: ‘any power wins from the logarithmic function’.

The exp and the log are each others inverses, so

$$\log(\exp(x)) = x \quad (11)$$

$$\exp(\log(x)) = x \quad (\text{for } x > 0) \quad (12)$$

2 Partial derivatives, gradient, nabla symbol

Let $f(x_1, \dots, x_n) = f(\mathbf{x})$ be a function of several variables. The gradient of f , denoted as ∇f (the symbol “ ∇ ” is called ‘nabla’), is the vector of all partial derivatives:

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)^T$$

NB, the partial derivative $\partial f(x_1, \dots, x_i, \dots, x_n)/\partial x_i$ is computed by taking the derivative with respect to x_i while keeping all other variables constant.

Example:

$$f(x, y, z) = xy^2 + 3.1yz$$

Then

$$\nabla f(x, y, z) = (y^2, 2xy + 3.1z, 3.1y)^T$$

At local minima (and maxima, and so-called saddle points) of a differentiable function f , the gradient is zero, i.e., $\nabla f = 0$.

Example:

$$f(x, y) = x^2 + y^2 + (y + 1)x$$

So

$$\nabla f(x, y) = (2x + y + 1, 2y + x)^T$$

Then we can compute the point (x^*, y^*) that minimizes f by setting $\nabla f = 0$,

$$\left. \begin{array}{l} 2x^* + y^* + 1 = 0 \\ 2y^* + x^* = 0 \end{array} \right\} \Rightarrow (x^*, y^*) = \left(-\frac{2}{3}, \frac{1}{3}\right) \quad (13)$$

2.1 Chain rule

Suppose f is a function of y_1, y_2, \dots, y_k and each y_j is a function of x , then we can compute the derivative of f with respect to x by the chain rule

$$\frac{df}{dx} = \sum_{j=1}^k \frac{\partial f}{\partial y_j} \frac{dy_j}{dx}$$

Example:

$$f(y(x), z(x)) = y(x)/z(x)$$

and $y(x) = x^4$ and $z = x^2$ then

$$\frac{df}{dx} = \frac{1}{z(x)} y'(x) - \frac{y(x)}{z(x)^2} z'(x) = 2x$$

3 Taylor series / Taylor expansions

3.1 Taylor expansion in one dimension

Assuming that $f(x)$ has derivatives of all orders in $x = a$, then the Taylor expansion of f around a is

$$f(a + \epsilon) = \sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} \epsilon^k = f(a) + \epsilon f'(a) + \frac{\epsilon^2}{2} f''(a) + \dots$$

The prefactors in the Taylor series can be checked by computing the Taylor expansion of a polynomial.

Linearization of a function around a is taking the Taylor expansion up to first order:

$$f(a + x) = f(a) + x f'(a)$$

Examples: check that for small x the following expansions are correct up to second order:

$$\begin{aligned} \sin(x) &= x \\ \cos(x) &= 1 - \frac{1}{2}x^2 \\ \exp(x) &= 1 + x + \frac{1}{2}x^2 \\ (1+x)^a &= 1 + ax + \frac{a(a-1)}{2}x^2 \\ \ln(1+x) &= x - \frac{1}{2}x^2 \end{aligned}$$

3.2 Taylor expansion in several dimensions

The Taylor expansion of a function of several variables, $f(x_1, \dots, x_n) = f(\mathbf{x})$ is (up to second order)

$$f(\mathbf{a} + \epsilon) = f(\mathbf{a}) + \epsilon^T \nabla f(\mathbf{a}) + \frac{1}{2} \epsilon^T H \epsilon$$

with H the Hessian, which is the symmetric matrix of partial derivatives

$$H_{ij} = \left. \frac{\partial^2}{\partial x_i \partial x_j} f(\mathbf{x}) \right|_{\mathbf{x}=\mathbf{a}}$$

4 Summations and Kronecker delta

If \mathbf{A} is a $N \times M$ matrix with entries A_{ij} and \mathbf{v} an M -dimensional vector with entries v_i , then $\mathbf{w} = \mathbf{A}\mathbf{v}$ is a N -dimensional vector with entries

$$w_i = \sum_{j=1}^M A_{ij} v_j \tag{14}$$

Similarly, if \mathbf{B} is a $M \times K$ matrix with entries B_{ij} , then $\mathbf{C} = \mathbf{A}\mathbf{B}$ is a $N \times K$ matrix with entries

$$C_{ik} = \sum_{j=1}^M A_{ij} B_{jk} \tag{15}$$

The notation δ_{ij} denotes usually the Kronecker delta symbol, i.e.,

$$\begin{cases} \delta_{ij} = 1 & \text{if } i = j \\ \delta_{ij} = 0 & \text{otherwise} \end{cases} \quad (16)$$

It has the nice property that it ‘eats’ dummy indices in summations:

$$\sum_{j=1}^M \delta_{ij} v_j = v_i \quad \text{for all } 1 \leq i \leq M \quad (17)$$

(The Kronecker delta can be viewed as the entries of the identity matrix \mathbf{I} . In vector notation, (17) is equivalent to the statement $\mathbf{I}\mathbf{v} = \mathbf{v}$.)

5 Dirac’s delta function

The Dirac delta function $\delta(x)$ is defined such that

$$\delta(x) = 0 \text{ if } x \neq 0 \quad \text{and} \quad \int_{-\infty}^{\infty} \delta(x) dx = 1$$

(actually, it is not a proper function, but that is another story). $\delta(x)$ is a spike (a peak) at $x = 0$. The function $\delta(x - x_0)$ as a function of x is a spike at x_0 . As a consequence of the definition, the delta function has important property

$$\int_{-\infty}^{\infty} f(x) \delta(x - x_0) = f(x_0)$$

see preface xiii.